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Comparative Study of Imputation Techniques for Missing Value Estimation in Particulate Matter 2.5 µm Time Series

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INTRODUCTION

Peru is a South American country with the worst air quality (Colorado, 2019). Thus, Lima is the second capital with the worst air quality after Santiago de Chile. A total of 12 cities in Peru have air pollution levels above those recommended (Republica, 2023) by the World Health Organization (WHO): Lima, Arequipa, Ica, Trujillo, Ucayali, Ancash, Apurimac, Cajamarca, Cusco, Madre de Dios, Moquegua, and Piura.

According to the World Bank, 79.6% of the energy consumed in Peru is derived from fossil fuels (RumboMinero, 2022), with an increasing trend. Another cause is aridity and lack of vegetation, which makes it easier for air currents to raise polluting particles. Air pollution, specifically PM2.5 and PM10, cause respiratory infections (Bu *et al*., 2021), throat irritation (Wyer *et al.*, 2022)though there have been several studies which indicate that NH3 has a direct effect on the respiratory health of those who handle livestock. These health impacts can include

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a reduced lung function, irritation to the throat and eyes, and increased coughing and phlegm expulsion. More recent studies have indicated that agricultural NH3 may directly influence the early on-set of asthma in young children. In addition to the potential direct impact of ammonia, it is also a substantial contributor to the fine particulate matter (PM2.5, cough, heart disease (Oh *et al*., 2023), stroke (Chen *et al*., 2022), and lung cancer (Huang *et al*., 2017).

Thus, the study of particulate matter 2.5 µm (PM2.5) time series is significant because, based on them, prediction models can be implemented, allowing the corresponding authorities to make decisions to safeguard the health of the population (Priya & Khanaa, 2023)air pollution is becoming a very big issue in metropolitan cities due to the availability of vehicles. This air pollution has spread various breathing-related diseases to people vigorously in recent years. People are affected much more severely due to the lack of knowledge and updates about the air pollution level in the specific area and dates. To safeguard the people and to provide enough knowledge about the air pollution level, many researchers have developed many air qualities during COVID-19 in prediction systems using various classifiers. Even though no system resolves this issue due to the rapid growth of the population, automobile usage, and industries. To fulfil the current requirements, this paper proposes an Intelligent Air Quality During COVID-19 Prediction and Monitoring System (IAQPMS.

However, before implementing the predictive models, reviewing the quality of the data acquired by the monitoring stations is necessary, which in most cases presents missing values (NAs) with different gap sizes, small, medium, and large, owing to various reasons, such as power outages, equipment malfunctions (Moritz & Bartz-Beielstein, 2017), and human errors. Most models based on machine and deep learning require data with no missing values. A simple treatment that is commonly performed involves eliminating records with missing values, but this can lead to the loss of valuable information. Therefore, finding the most appropriate technique/ model to estimate these types of values is crucial.

The process of estimating missing values is known as imputation, and, according to the state of the art, several techniques exist for this process. Among them, autoregressive integrated moving average (ARIMA) (Moritz, 2021), spline interpolation (Moritz & Bartz-Beielstein, 2017), Stineman interpolation (Moritz & Bartz-Beielstein, 2017), exponential weighted moving average (EWMA) (Moritz, 2021), linear weighted moving average (LWMA) (Moritz, 2021), local average of nearest neighbors (LANN) (Flores *et al*., 2019)"ISSN":"21565570","abstract":"The imputation of time series is one of the most important tasks in the homogenization process, the quality and precision of this process will directly influence the accuracy of the time series predictions. This paper proposes two simple algorithms, but quite powerful for univariate time series imputation process, which are based on the means of the nearest neighbors for the imputation of missing data. The first of them Local Average of Neighbors Neighbors (LANN, multiple imputation by chained equations (MICE) (Peker & Kubat, 2021), K-nearest neighbors (KNN), long short-term memory (LSTM) (Sak *et al*., 2014)we explore LSTM RNN architectures for large scale acoustic modeling in speech recognition. We recently showed that LSTM RNNs are more effective than DNNs and conventional RNNs for acoustic modeling, considering moderately-sized models trained on a single machine. Here, we introduce the first distributed training of LSTM RNNs using asynchronous stochastic gradient descent optimization on a large cluster of machines. We show that a two-layer deep LSTM RNN where each LSTM layer has a linear recurrent projection layer can exceed state-of-the-art speech recognition performance. This architecture makes more effective use of model parameters than the others considered, converges quickly, and outperforms a deep feed forward neural network having an order of magnitude more parameters.","author":[{"dropping-particle","","family":

"Sak","given":"Haşim","non-dropping-particle":"","parse-names":false,"suffix":""},{"dropping-particle":"","family":"Senior","given":"Andrew","non-dropping-particle":"","parse-nam es":false,"suffix":""},{"dropping-particle":"","family":"Beaufays","given":"Françoise","nondropping-particle":"","parse-names":false,"suffix":""}],"container-title":"Proceedings of the Annual Conference of the International Speech Communication Association, INTERSPEECH","id":"ITEM-1","issued":{"date-parts":[["2014"]]},"title":"Long short-term memory recurrent neural network architectures for large scale acoustic modeling","type":"paperconference"},"uris":["http://www.mendeley.com/documents/?uuid=4b74cfe0-e638-3127 ba9f-87329bc8f067"]}],"mendeley":{"formattedCitation":"(Sak et al., 2014, and gated recurrent unit (GRU) (Chung *et al*., 2014)we focus on more sophisticated units that implement a gating mechanism, such as a long short-term memory (LSTM. ARIMA, EWMA, LWMA, and LANN are moving average techniques, spline and Stineman are techniques based on interpolation, and LSTM and GRU are techniques based on deep learning. These are much more recent than the previous ones, whose main difference lies in the amount of data for their training to obtain satisfactory results.

According to the literature, studies on PM2.5, in Lima City, mostly address the correlation between PM2.5 volumes and various variables, such as cardiorespiratory emergency cases (V. Tapia *et al*., 2020)(Vilma Tapia *et al*., 2020), asthma emergency cases (Vu *et al*., 2021), maternal exposure (V. L. Tapia *et al*., 2020)034 births from 2012 to 2016, at three public hospitals. We used estimated daily PM2.5 from a newly created model developed using ground measurements, satellite data, and a chemical transport model. Exposure was assigned based on district of residence (n = 39, overweight/obesity, and covid-19 cases (Vasquez-Apestegui *et al*., 2021). Other studies have addressed this analytically, using trends (Reátegui-Romero *et al*., 2021)(Rojas *et al*., 2022), and volumes (Reátegui-Romero *et al*., 2018). No studies have analyzed the estimation of missing or NA values for any monitoring station in Lima City. This served as the motivation for conducting a comparative study of imputation techniques for the PM2.5 time series from the city of Lima, Peru.

In this study, ARIMA, spline interpolation, EWMA, LWMA, LANN, LSTM, BiLSTM, GRU, and BiGRU were implemented for short-gaps of missing values, with our main contribution being the comparative study of imputation techniques to estimate short-gaps of missing values in PM2.5 time series of Lima City.

The remainder of the paper is organized as follows: Section 2 presents the methodology where the experiments are described; Section 3 describes the results; and finally, the conclusions of the study are presented.

MATERIAL AND METHODS

The dataset

The dataset was downloaded from openaq.org, and corresponds to the Ceres station which is located in the Ate district of Lima city in Peru, with latitude -12.028694 and longitude: -76.927056 at 300 masl. It contains hourly data from 2021-12-24 07:00 :00 hours to 2024-02- 29 00:00:00 hours with a total of 11,822 available records. The Ceres monitoring station can be seen in Fig.1 in orange color and the 103 number.

It is important to highlight that from 2021-12-24 the dataset should contain 19,146 records, however, there were only 11,822 records, which means that 7,324 records were not recorded, they represented missing values. In this study, only the available data were used. Fig.2 shows the available data plotted.

Data preparation

Data were downloaded in files of 1,000 records, and the first step was to join them in just one file. Once the records were in a single file, the next step was to organize them into two partitions, training 80% equivalent to 9,456 records, and the remaining 20% for testing equivalent to 2,366 records. Fig. 3 shows training and testing data.

The test data was structured with three simple strategies, the first inserts missing values (NA) every three items, the second every two items, and the third every 1 item. Each strategy generates 25%, 33%, and 50% of missing values respectively. A clearer appreciation is shown in Table 1.

Fig. 1. The air monitoring stations of Lima city

Fig. 2. Available Pm2.5 time series of Ceres Station in Lima city. **Fig. 2.** Available Pm2.5 time series of Ceres Station in Lima city

Fig. 3. Training and testing data. **Fig. 3.** Training and testing data.

NA stands for Not Available values

Table 2. Parameters for Moving Average-based techniques and Spline interpolation **Table 2.** Parameters for Moving Average-based techniques and Spline interpolation

Technique	Function	Parameters	
ARIMA	na kalman	model=auto.arima	
Spline	na interpolation	option='spline'	
EWMA	na ma	$k=8$, weighting='exponential'	
LWMA	na ma	$K=2$, weighting='linear'	
LANN	na ma	$k=2$, weighting='simple'	

Implementation of Techniques/Models

In this phase, different imputation techniques were implemented. ARIMA, Spline, EWMA, LWMA, and LANN were implemented through the imputeTS library(Moritz, 2021) in RStudio. The respective parameters are shown in Table 2.

The techniques based on deep learning e.g. LSTM, BiLSTM, GRU, and BiGRU were implemented using the Tensorflow 2.9.0 library in Python language considering the hyperparameters shown in Table 3.

Each model had 4 layers, the first three were of model type and the last layer was Dense with sigmoid as the activation function. The models were compiled with loss function = 'mse', optimizer = 'adam', and 100 epochs.

The results achieved by each model are shown in the Results and Discussion section.

Evaluation

The implemented techniques were evaluated through three well-known metrics including Root Mean Squared Error (RMSE)(1) which measures the error between the observed and predicted data. Mean Absolute Percentage Error (MAPE)(2), which measures the error in a similar way to RMSE, but expressed in percentage terms, is more useful than the previous ones if it is necessary to compare results from different datasets. Finally, the correlation between the actual data and the estimated/predicted data is measured by $R^2(3)$.

$$
RMSE = \sqrt{\frac{\sum_{i=1}^{n} (Pi - Oi)^2}{n}}
$$
 (1)

$$
MAPE = \frac{1}{n} \sum_{i=1}^{n} \left| \frac{(O_i - P_i)}{O_i} \right| \neq 100
$$
 (2)

$$
R^{2} = \left(\sum_{i=1}^{n} \left(O_{i} - \overline{O}\right) \left(P_{i} - \overline{P}\right) / \sum_{i=1}^{n} \left(O_{i} - \overline{O}\right)^{2} \sum_{i=1}^{n} \left(P_{i} - \overline{P}\right)^{2})\right)
$$
(3)

RESULTS AND DISCUSSION

This section describes the results that were achieved after the modeling phase.

According to Table 4, for 25% of missing values (NA), the best models, in terms of RMSE, MAPE, and R^2 were ARIMA, Spline interpolation, and LWMA with RMSEs of 7.1746 μ m/ m³, 7.2646 μm/m³, 8.3427 μm/m³; MAPEs of 9.7689%, 10.8286%, 11.5104%; R²s of 0.8278, 0.8316, and 0.7672 respectively. A graphical view of the observed vs predicted data can be seen in Fig. 4. Predicted data correspond to the best moving averages technique (ARIMA), and the best deep learning model (BiLSTM).

Technique	Hyperparameters
LSTM	[30,30,30,1] activation='relu', dropout='0.1', learning rate='1e-3'
BILSTM	[30,30,30,1] activation='relu' dropout='0.1', learning rate=' $1e-3$ '
GRU	[30,30,30,1] activation='relu' dropout='0.1', learning rate=' $1e-3'$ '
BiGRU	[30,30,30,1] activation='relu' dropout='0.1', learning rate=' $1e-3'$ '

Table 3. Hyperparameters for deep learning models **Table 3.** Hyperparameters for deep learning models

Table 4. Results on test data with 25% of missing values **Table 4.** Results on test data with 25% of missing values

Model	RMSE	MAPE	\mathbf{R}^2
ARIMA	7.1746	9.7689	0.8278
SPLINE	7.2646	10.8286	0.8316
EWMA	8.6002	12.7682	0.7546
LWMA	8.3427	11.5104	0.7672
LANN	8.7725	12.1900	0.7426
LSTM	10.5402	21.4211	0.6975
BILSTM	9.7553	14.8956	0.6946
GRU	10.4131	16.2035	10.4091
BIGRU	10.4092	15.3246	0.6792

Fig. 4. Predicted values. ARIMA vs BiLSTM (25% of missing values)

Model	RMSE	MAPE	\mathbf{R}^2
ARIMA	8.0642	11.8268	0.7726
SPLINE	8.8064	12.2399	0.7686
EWMA	8.5643	13.4677	0.7423
LWMA	8.5524	12.3646	0.7473
LANN	8.7510	12.8295	0.7341
LSTM	10.4083	21.5205	0.7000
BILSTM	9.6255	13.8829	0.6947
GRU	10.4269	14.8330	0.6967
BIGRU	10.5230	14.3942	0.6715

Table 5. Results on test data with 33% of missing values **Table 5.** Results on test data with 33% of missing values

According to Table 5, for 33% of missing values, the best models, in terms of RMSE were ARIMA, LWMA, and EWMA with RMSEs of 8.0642 μ m/m³, 8.5524 μ m/m³, and 8.5643 μ m/ $m³$ respectively. In terms of MAPE and $R²$ were: ARIMA, Spline, and LWMA with MAPEs of 11.8268%, 12.2399%, 12.3646, and R²s of 0.7726, 0.7686, and 0.7473 respectively.

A graphical view of the observed and predicted data can be seen in Fig. 5.

According to Table 6, for 50% of missing values, the best models in terms of RMSE are ARIMA, LWMA, and LANN with similar RMSEs of $7.3623 \mu m/m³$. In terms of MAPE the same models with MAPEs of 10.0192%, 10.0197%, and 10.0198% respectively. Finally, in terms of \mathbb{R}^2 , similar to RMSE, the three models presented the same \mathbb{R}^2 of 0.8247.

A graphical view of the observed and predicted data can be seen in Fig. 6.

According to the results obtained, it can be seen that for short-gaps of missing values, in different configurations (25%, 33%, and 50%) the best model to estimate this type of values was ARIMA, which is within the set of moving average-based models. The best Deep learningbased model was BiLSTM which is in sixth place.

Although the classic models outperformed the deep learning models in the different configurations of missing values, according to the literature, a model is excellent if it has a MAPE lower than 10%, considering this, ARIMA is the one model that achieved this rating

Fig. 5. Predicted values. ARIMA vs BiLSTM (33% of missing values)

Model	RMSE	MAPE	\mathbb{R}^2
ARIMA	7.3623	10.0192	0.8247
SPLINE	7.4536	10.5615	0.8235
EWMA	8.0967	12.2998	0.7924
LWMA	7.3623	10.0197	0.8247
LANN	7.3623	10.0198	0.8247
LSTM	10.3925	21.5006	0.7141
BILSTM	9.4765	14.1246	0.7149
GRU	9.9464	15.7523	0.7199
BIGRU	9.7511	14.6528	0.7132

Table 6. Results on test data with 50% of missing values **Table 6.** Results on test data with 50% of missing values

for the configuration of 25% of missing values with MAPE of 9.7689%. This means that the implemented models still need to be improved.

It is important to highlight that the implemented models based on moving averages in this study only used test data to estimate the different configurations of missing values, while the deep learning-based models used the training data for their respective training, even so, they were surpassed by the first ones.

According to the literature, for various regression tasks, deep learning models outperformed moving average models, but these require a greater amount of data. As reported in different works, hourly data of 2 or 3 years was insufficient to achieve good results.

Table 7 shows the results obtained by different techniques or models for PMPM2.5 time series imputation.

In terms of RMSE, which is not the most appropriate metric to compare the results of different datasets, however, it was appreciated that the best result of the related works was reported by (Alkabbani *et al*., 2022)timely air quality index (AQI with an RMSE of 3,756 **µ**m/m³ using the machine learning technique known as Random Forest. The second-best work was reported by (Flores *et al*., 2023) with an RMSE of 6.8369 **µ**m/m³ using deep learning and polynomial

Fig. 6. Predicted values. ARIMA vs BiLSTM (50% NAs)

interpolation. And, this work using ARIMA was located in the third position with an RMSE of 7.1746 **µ**m/m³ .

In terms of \mathbb{R}^2 , which is better than RMSE for comparing results of different datasets, but unfortunately, few related works reported results with $R²$. The best result was reported by (Lee *et al.*, 2023) with an \mathbb{R}^2 of 0.895, followed by ARIMA of this study with an \mathbb{R}^2 of 0.8278 in the set of 25% of missing values.

CONCLUSION

According to the results obtained, it can be stated that for imputation of short-gaps in hourly PM2.5 time series of fewer than 3 years, it is more appropriate or pertinent to use techniques based on moving averages such as ARIMA, EWMA, LWMA, LANN or techniques based in interpolation such as Spline, instead of resorting to more complex techniques such as those based on Deep learning including LSTM, BiLSTM, GRU and BiGRU.

GRANT SUPPORT DETAILS

The present research did not receive any financial support.

CONFLICT OF INTEREST

The authors declare that there is not any conflict of interest regarding the publication of this manuscript. In addition, the ethical issues, including plagiarism, informed consent, misconduct, data fabrication and/ or falsification, double publication and/or submission, and redundancy have been completely observed by the authors.

LIFE SCIENCE REPORTING

No life science threat was practiced in this research.

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